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Call for Papers – Open Invited Session

Deep Learning based Perception for Autonomous Vehicle

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Recently, interests in self-driving cars have been increased, and sensors such as cameras, LIDAR, and radar are used to perception for self-driving. Perception of the surrounding environment, vehicles, and pedestrians is essential for autonomous driving, and for this purpose, deep learning-based recognition is being actively researched. In this invited session, various perception technologies for autonomous vehicles such as deep learning-based object recognition, SLAM, object tracking, and lane detection have been introduced

We welcome contributions on this research topic. Please visit our website for details.

<https://2023.iccas.org>