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Call for Papers – Open Invited Session

Autonomous Driving for Future Mobility

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The platform for autonomous driving has changed from the conventional vehicle to the future mobility based on the modular corner platform. The modular corner module provides the four-wheel independent steering, driving, and braking to extend the operational design domain of autonomous driving. This session presents various motion planning and control methodologies for the modular corner-based autonomous driving platform and other types of future mobility.

We welcome contributions on this research topic. Please visit our website for details.

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